High Performance Computing in Julia from the ground up.

**Multithreading**

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# Multithreading

- Each process can spin up multiple **threads** to enable concurrent processing
- Each thread has access to all the shared memory in a process
- Very **cheap** to spin up new threads (as opposed to starting a new process)
- If there are multiple cores available, each thread can be executed on a different core in **parallel**
- Shared memory introduces new challenges, namely **race conditions** which need to be addressed by **atomics**, **mutexes**, **semaphores** or **algorithm re-design**.

### Race Conditions

- If two threads are trying to write & read from the **same block** of memory at the same time.
- Race conditions usually do not cause the program to crash, but often just produce the **wrong** results
- Typical examples:
	- Mutating an array or variable (i.e. a counter)
	- Appending to an array
	- Random number generation
- Functions/Operations that avoid race conditions are known as **thread-safe**

# Mitigating Race Conditions

Atomics

• Atomic operations are designed to be indivisible so that you can guarantee that the operations will happen sequentially

#### **Race Condition**

using Base.Threads

function my\_sum(numbers::Vector{Int})

 $s = 0$ @threads for n in numbers  $s$  +=  $n$ end return s

end

#### **Thread-Safe (with Atomics)**

function my\_sum(numbers::Vector{Int})  $s =$  Atomic{Int}(0) @threads for n in numbers atomic\_add!(s, n) end return s[] end

#### **Advantages**

- Fixes the race conditions
- Guarantees thread-safety if used correctly
- Can be used as part of the solution

#### **Disadvantages**

- Atomic operations are **much slower** than non-atomic counterparts
- Causes threads to **sleep** while waiting to write
- Can cause a higher slowdown with more threads
- Usually means that algorithm is badly designed

#### **Benchmarks**

```
julia> @btime sum($numbers)
        46.328 ms (0 allocations: 0 bytes)
      julia> @btime my_sum($numbers)
        1.144 s (26 allocations: 2.64 KiB)
      julia> @btime my_sum_chunked($numbers)
        14.982 ms (27 allocations: 2.86 KiB)
25x
```
#### **Performant Version (Chunked)**

```
import Base.Iterators: partition
function my_sum_chunked(numbers::Vector{Int})
    s = Atomic{Int}(0)
    block size = cld(length(numbers), nthreads())iter = collect(partition(numbers, block size))
   @threads for nums in iter
        atomic add!(s, sum(nums))
    end
    return s[]
end
```
#### **Benchmarks**

julia> @btime sum(\$numbers) 46.328 ms (0 allocations: 0 bytes) julia> @btime my\_sum(\$numbers) 1.144 s (26 allocations: 2.64 KiB) julia> @btime my\_sum\_chunked(\$numbers) 14.982 ms (27 allocations: 2.86 KiB)

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   @threads for nums in iter
        atomic add!(s, sum(nums))
    end
   return s[]
end
```
# Mitigating Race Conditions

Mutexes and Semaphores

# Mutexes vs Semaphores

#### **Mutexes**

- A mutex provides **mutual exclusion**, which means that only one worker can access a resource at any one time
- Can be implemented as a "**lock**" where it can be either unlocked or locked.

#### **Semaphores**

- A semaphore generalises the **mutex**
- Instead of one resource, this provides a "**pool**" of resources
- E.g. a pool of memory buffers
- Resources can be added back into the pool when usage is not required

#### Mutexes in Julia

• We use the ReentrantLock() to act as a **mutex**

```
function my_sum_mutex(numbers::Vector{Int})
    s = 0lk = ReentrantLock()
   @threads for n in numbers
        lock(lk) do
            S += nend
    end
    return s
end
```
#### Mutexes in Julia

• We use the ReentrantLock() to act as a **mutex**

```
function my_sum_mutex(numbers::Vector{Int})
    s = 01k = ReentrantLock()j The lock is a standalone variable
   @threads for n in numbers
        lock(lk) do
            S += nend
    end
    return s
end
```
### Mutexes in Julia

• We use the ReentrantLock() to act as a **mutex**

```
function my_sum_mutex(numbers::Vector{Int})
```

```
s = 0lk = ReentrantLock()
    @threads for n in numbers
       lock(lk) do
            S += nend
    end
    return s
end
```
- The lock function attempts to **acquire** the mutex
- When acquired it will execute the code in the "do" block
- When finished executing, the thread **relinquishes** the lock so it can be acquired by another thread
- Threads will automatically **wait** to acquire a lock

```
function my_sum_channel(numbers::Vector{Int})
    num buffers = 4pool = Channel{Int}(num_buffers)
    for i in 1:num_buffers
       put!(pool, 0)
    end
    @threads for n in numbers
       s = take!(pool)s + = nput!(pool, s)
    end
    s = 0for i in 1:num_buffers
       s += take! (pool)
    end
    close(pool)
    return s
```

```
function my_sum_channel(numbers::Vector{Int})
   num buffers = 4pool = Channel{Int}(num buffers)for i in 1:num_buffers
      put!(pool, 0)
   end
   @threads for n in numbers
      s = take!(pool)s + = nput!(pool, s)
   end
   s = 0for i in 1:num_buffers
      s += take!(pool)
   end
   close(pool)
   return s
end
                                    Create a pool of resources to use with 
                                    a maximum capacity of 4
```

```
function my_sum_channel(numbers::Vector{Int})
   num buffers = 4pool = Channel{Int}(num buffers)for i in 1:num_buffers
      put!(pool, 0)
   end
   @threads for n in numbers
      s = take!(pool)
       s + = nput!(pool, s)
   end
   s = 0for i in 1:num_buffers
       s += take!(pool)
   end
   close(pool)
   return s
end
                          Acquire one of the resources from the pool
```

```
function my_sum_channel(numbers::Vector{Int})
   num buffers = 4pool = Channel{Int}(num buffers)for i in 1:num_buffers
       put!(pool, 0)
   end
   @threads for n in numbers
       s = take!(pool)s + = nput!(pool, s)end
   s = 0for i in 1:num_buffers
       s += take!(pool)
   end
   close(pool)
   return s
end
                      Put it back in the pool when finished
```

```
function my sum channel(numbers::Vector{Int})
   num buffers = 4pool = Channel{Int}(num buffers)for i in 1:num_buffers
       put!(pool, 0)
   end
   @threads for n in numbers
       s = take!(pool)s + = nput!(pool, s)
   end
   \mathsf{s} = \mathsf{0}for i in 1:num buffers
       s += take!(pool)
   lend
   close(pool)
   return s
                           Combine the resources 
                           together and close the pool
```
# Mitigating Race Conditions

Separate Memory Per Thread

```
function est pi mc threaded(n)
    n cs = zeros(typeof(n), Threads.nthreads())
    Threads @threads for _ in 1:n
        # Choose random numbers between -1 and +1 for x and y
        x = rand() * 2 - 1y = rand() * 2 - 1# Work out the distance from origin using Pythagoras
        r2 = x * x + y * y# Count point if it is inside the circle (r^2=1)if r2 \leq 1n cs[Threads.threadid()] += 1end
    end
   n = sum(n cs)return 4 * n c / nend
```


Thread 1 Thread 2 Thread 3 Thread 4

```
function est pi mc threaded(n)
  [n_c s = zeros(typeof(n), Threads.nthreads())Threads @threads for _ in 1:n
        # Choose random numbers between -1 and +1 for x and y
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    end
   n = sum(n cs)return 4 * n c / nend
```








# False Sharing

- False sharing is a performance degrading bug, which can occur in sharedmemory multithreading code
- The CPU cache collects **contiguous chunks** of memory called **cache lines**
- As elements of an array are stored contiguously (i.e. next to each other), adjacent elements are usually sharing a **cache line**
- Each CPU core has its own L1 cache, which stores the cache line
- If **one** CPU core modifies the cache line, it is **invalidated** across **all** CPU caches
- This will force a **reload** of the cache from memory **despite** it not being logically required



Thread 1 Thread 2 Thread 3 Thread 4

```
function est_pi_mc_threaded(n)
   n_c s = zeros(typeeof(n), Threads.nthreads())Threads @threads for _ in 1:n
       # Choose random numbers between -1 and +1 for x and y
       x = rand() * 2 - 1y = rand() * 2 - 1# Work out the distance from origin using Pythagoras
       r2 = x * x + y * y# Count point if it is inside the circle (r^2=1)if r2 \leq 1n cs[Threads.threadid()] += 1end
   end
   n = sum(n cs)return 4 * n_c / nend
```


Thread 1 Thread 2 Thread 3 Thread 4

```
function est pi mc threaded spaced(n, spacing=1)
    n_c s = zeros(typeeff(n), Threads.nthreads()*spacing)
    Threads @threads for _ in 1:n
        x = rand() * 2 - 1y = rand() * 2 - 1r2 = x * x + y * yif r2 \leq 1n cs[Threads.threadid()*spacing] += 1end
    end
    n_c = sum(n_c s)return 4 * n_c / nend
```


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    n_c s = zeros(typeeff(n), Threads.nthreads()*spacing)
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    Threads @threads for _ in 1:n
        x = rand() * 2 - 1y = rand() * 2 - 1r2 = x * x + y * yif r2 \leq 1n_c s[Threads.threadid()*spacing] += 1
        end
    end
    n_c = sum(n_c s)return 4 * n_c / nend
```


```
function est pi mc threaded spaced(n, spacing=1)
    n_ccs = zeros(typeof(n), Threads.nthreads()*spacing)
    Threads @threads for _ in 1:n
        x = rand() * 2 - 1y = rand() * 2 - 1r2 = x * x + y * yif r2 \leq 1n cs[Threads.threadid()*spacing] += 1end
    end
    n_c = sum(n_c s)return 4 * n_c / nend
```






```
function is_dart_hit()
    x = rand() * 2 - 1y = rand() * 2 - 1return (x^2 + y^2 \leq 1)end
function est_pi_mc_threaded_chunked(n)
    n\_total = Atomic{Int}(block_size = cld(n, nthreads())@threads for t in 1:nthreads()
        n_c = mapreduce(x->is dart hit(), +, 1:block size)
        atomic add!(n total, n c)
    end
    return 4 * n_total[] / n
```
end









**Assignment Link:**

<https://classroom.github.com/a/HqKUZUwc>

**Task:**

**Q1)** Fix a race condition

**Q2)** Create a DAG for the dependices of a calculation and parallelise it with "**Threads.@spawn**" and "**fetch**"

**Q3)** Parallelise the N-body force calculation